



US waves propagation in an elastic medium: 2D Finite Element Modelling

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Introduction - Scope

US propagation interpretation in solid tricky due to the risk of correlated effects of microstructure evolution + effects of geometry



Perhaps FEM could help to understand and decorrelate the influence of different parameters (texture, grain size, ...)

- feasibility?

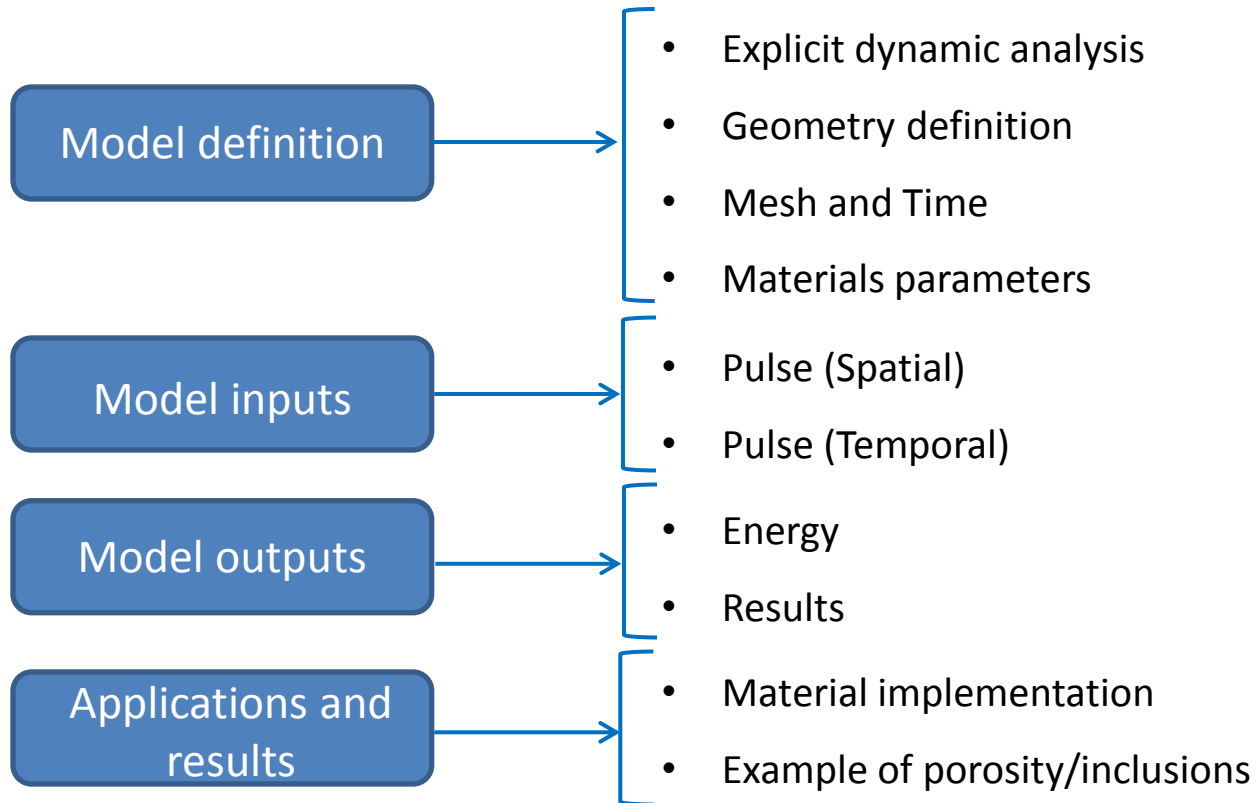
FEM consists in the division of space in many sub-domains to approximate the global response of a larger structure ... scale ratio = number of elements

	$\frac{\text{Larger structure scale}}{\text{Sub - domain scale}} = \frac{\text{mm}}{\mu\text{m}}$	
1D	$\frac{\text{mm}}{\mu\text{m}} \sim 10^3$	- yes, interest?
2D	$\frac{\text{mm}^2}{\mu\text{m}^2} \sim 10^6$	- possible
3D	$\frac{\text{mm}^3}{\mu\text{m}^3} \sim 10^9$	- Not on our computers!

Keep in mind ...
influence in 3D

Outline

Introduction

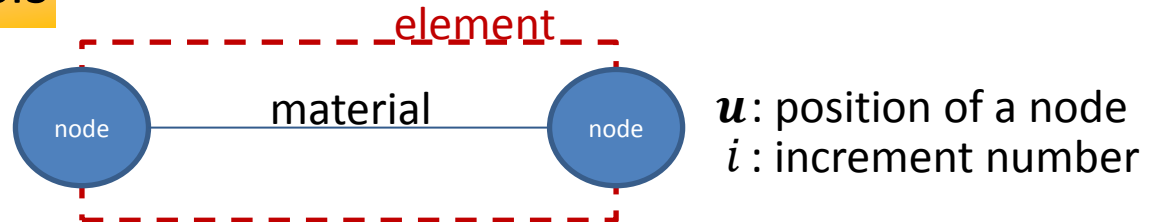


Conclusion

Model definition

Explicit dynamic analysis

ABAQUS user manual



- Diagonal element mass matrix \mathbf{M}
 = mass concentrated at nodes

$$\ddot{\mathbf{u}}^{(i)} = \mathbf{M}^{-1} \cdot (\mathbf{F}^{(i)} - \mathbf{I}^{(i)})$$

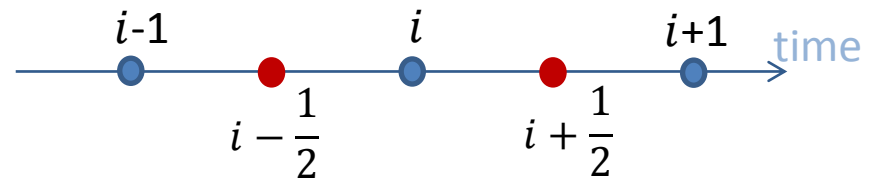
$\mathbf{F}^{(i)}$: external applied forces

$\mathbf{I}^{(i)}$: internal element forces

- Strains and stresses (constitutive laws)

- Explicit integration rule

$$f(i+1) = f(i) + f'(i) \cdot \Delta t$$



$$\text{central difference} \begin{cases} \dot{\mathbf{u}}^{(i+\frac{1}{2})} = \dot{\mathbf{u}}^{(i-\frac{1}{2})} + \frac{\Delta t^{(i+1)} + \Delta t^{(i)}}{2} \cdot \ddot{\mathbf{u}}^{(i)} \\ \mathbf{u}^{(i+1)} = \mathbf{u}^{(i)} + \Delta t \cdot \dot{\mathbf{u}}^{(i+\frac{1}{2})} \end{cases}$$

Explicit integration rule conditionally stable: above limit of time increment

$$\Delta t = \min \left(\frac{L_e}{c_d} \right)$$

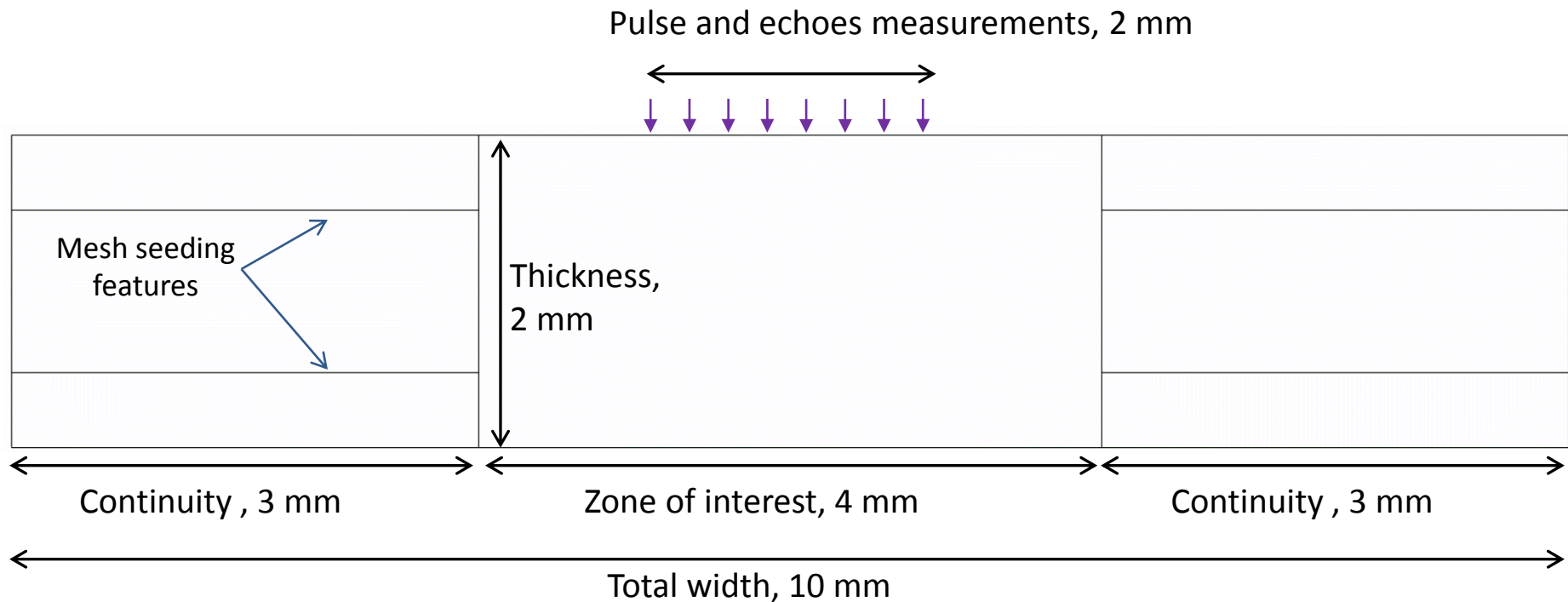
L_e : element dimension

c_d : dilatational wave speed

Model definition

Geometry

Typical sizes from experimental setup



Model definition

Mesh and time

Element type:
CPE4R

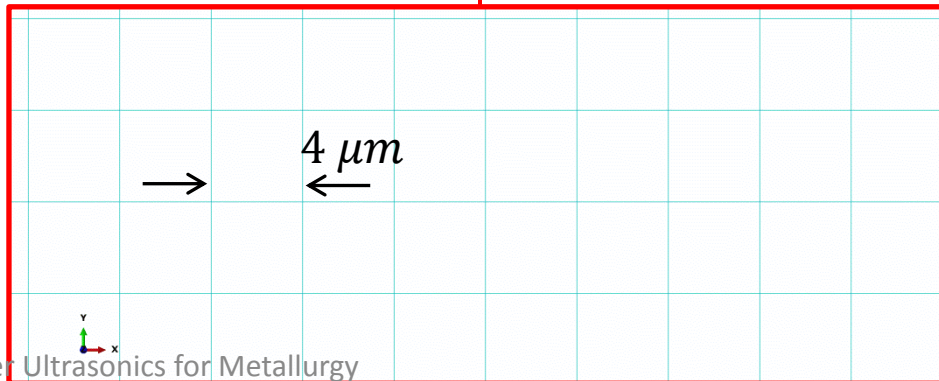
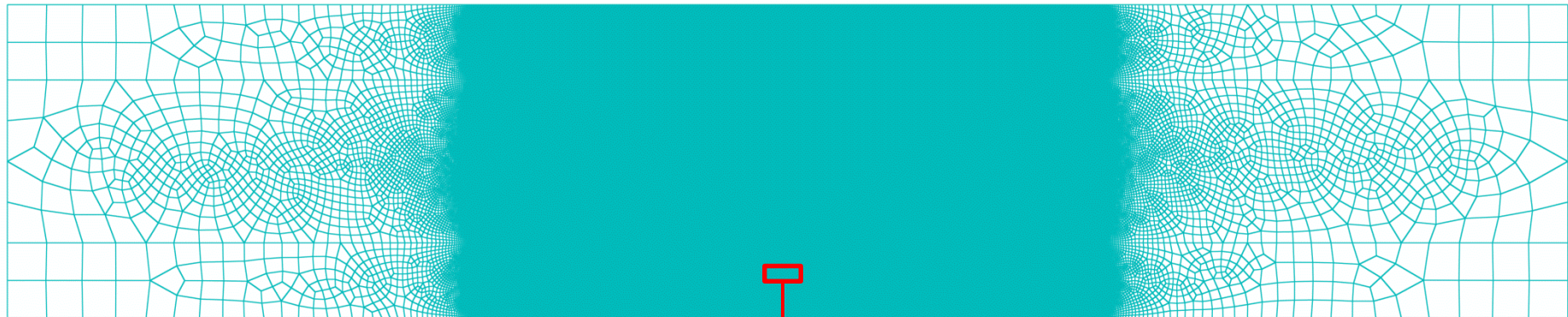
- continuous
- plane strain
- 4 nodes
- reduced integration

Mesh size ?

There are two spatial scales that have to be consider:

- the minimal wavelength;
- the scale of microstructure (grain size, porosity, inclusion ...).

$$\lambda_{min} = \frac{c}{f_{max}} \sim \frac{5000 \text{ m.s}^{-1}}{100 \text{ MHz}} = 50 \mu\text{m} \Rightarrow L_{min} = \frac{\lambda_{min}}{10} = 5 \mu\text{m}$$



$$\Delta t = \min \left(\frac{L_e}{c_d} \right) = 8.10^{-10} \text{ s}$$

$$\Delta t = 2.10^{-10} \text{ s}$$

Model definition

Material parameters *Remark on units: mm - N - tonne - MPa - s - mJ - tonne/mm³*

Minimum requested for an isotropic material: ρ, E, ν

For a fully anisotropic material definition: 21 coefficients

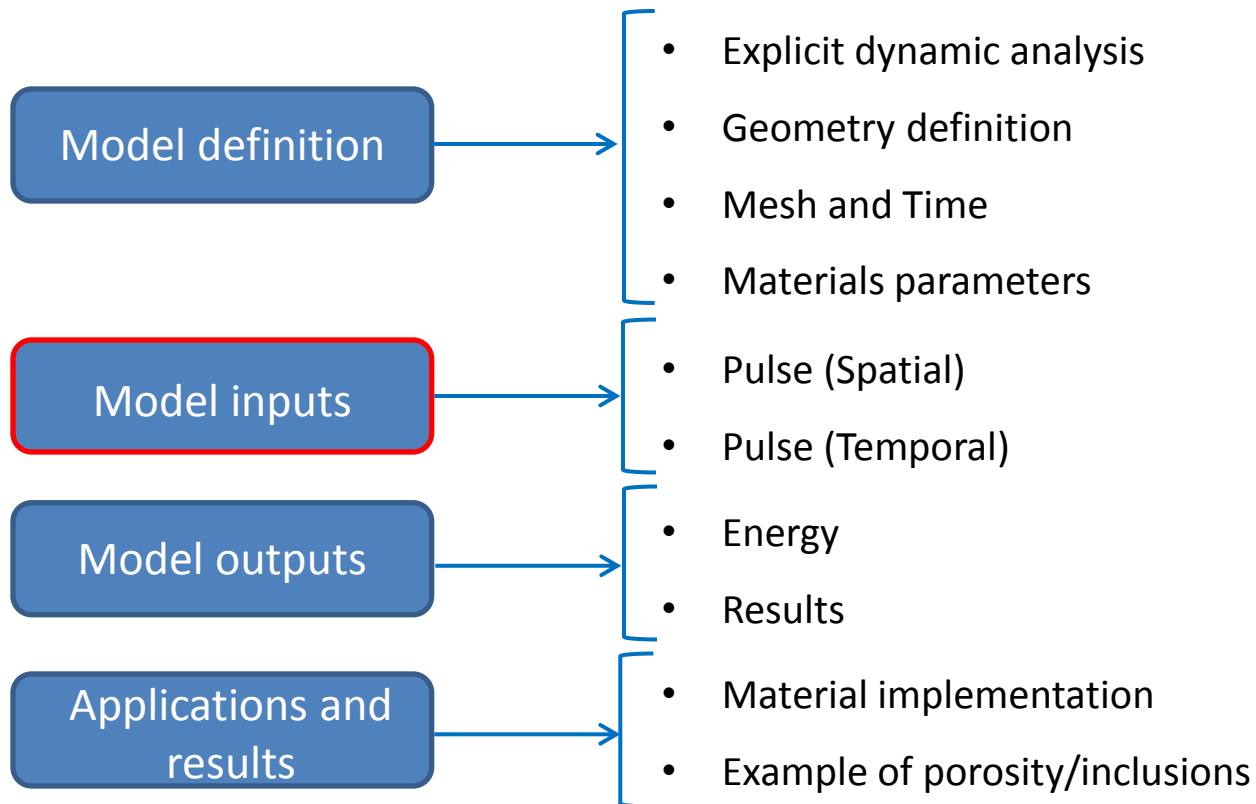
$$\begin{Bmatrix} \sigma_{11} \\ \sigma_{22} \\ \sigma_{33} \\ \sigma_{12} \\ \sigma_{13} \\ \sigma_{23} \end{Bmatrix} = \begin{bmatrix} D_{1111} & D_{1122} & D_{1133} & D_{1112} & D_{1113} & D_{1123} \\ & D_{2222} & D_{2233} & D_{2212} & D_{2213} & D_{2223} \\ & & D_{3333} & D_{3312} & D_{3313} & D_{3323} \\ & & & D_{1212} & D_{1213} & D_{1223} \\ & sym & & D_{1313} & D_{1323} & \\ & & & & D_{2323} & \end{bmatrix} \begin{Bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ \gamma_{12} \\ \gamma_{13} \\ \gamma_{23} \end{Bmatrix} = [D^{el}] \begin{Bmatrix} \varepsilon_{11} \\ \varepsilon_{22} \\ \varepsilon_{33} \\ \gamma_{12} \\ \gamma_{13} \\ \gamma_{23} \end{Bmatrix}.$$

Material orientation has to be defined, but without out of plane rotations, due to plane strain definition

The rotation are applied to the matrix and implemented only afterwards in the model

Outline

Introduction



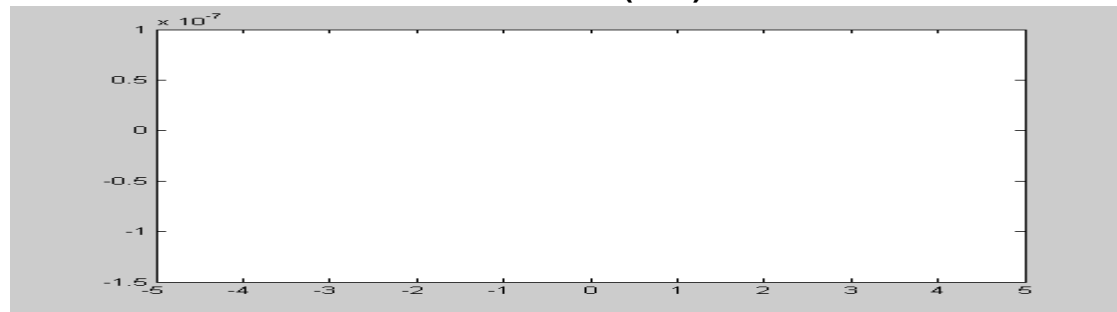
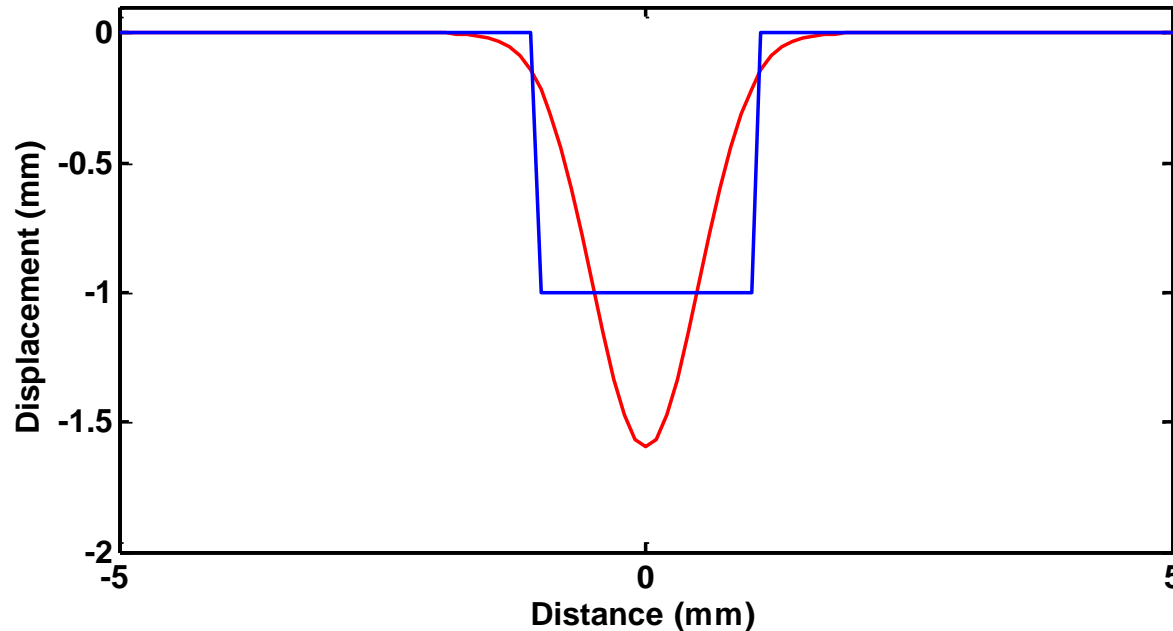
Conclusion

Model input

Pulse spatial definition

Top surface imposed displacement amplitude ≈ 0.1 nm

Shape:

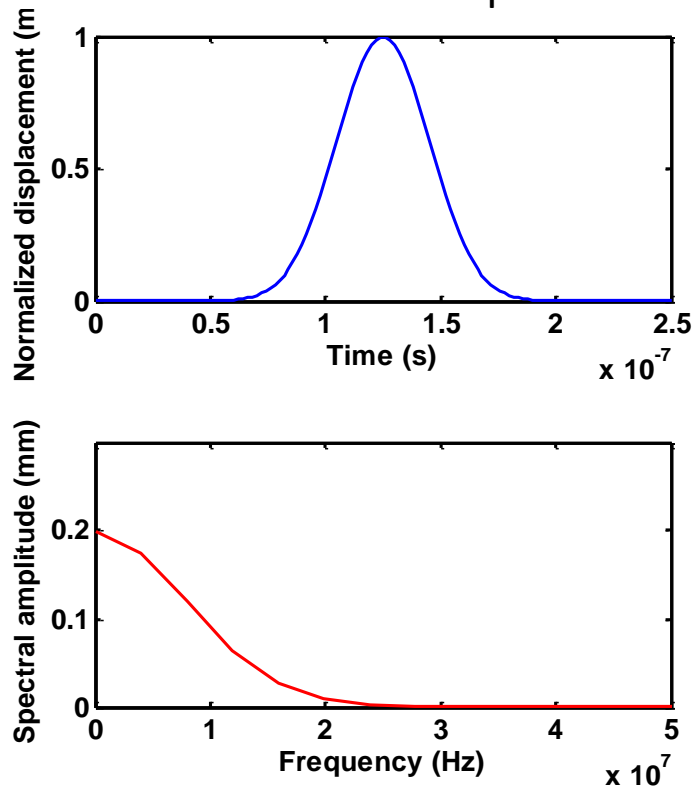


Gaussian pulse is chosen to avoid strong discontinuities

Model input

Pulse temporal definition

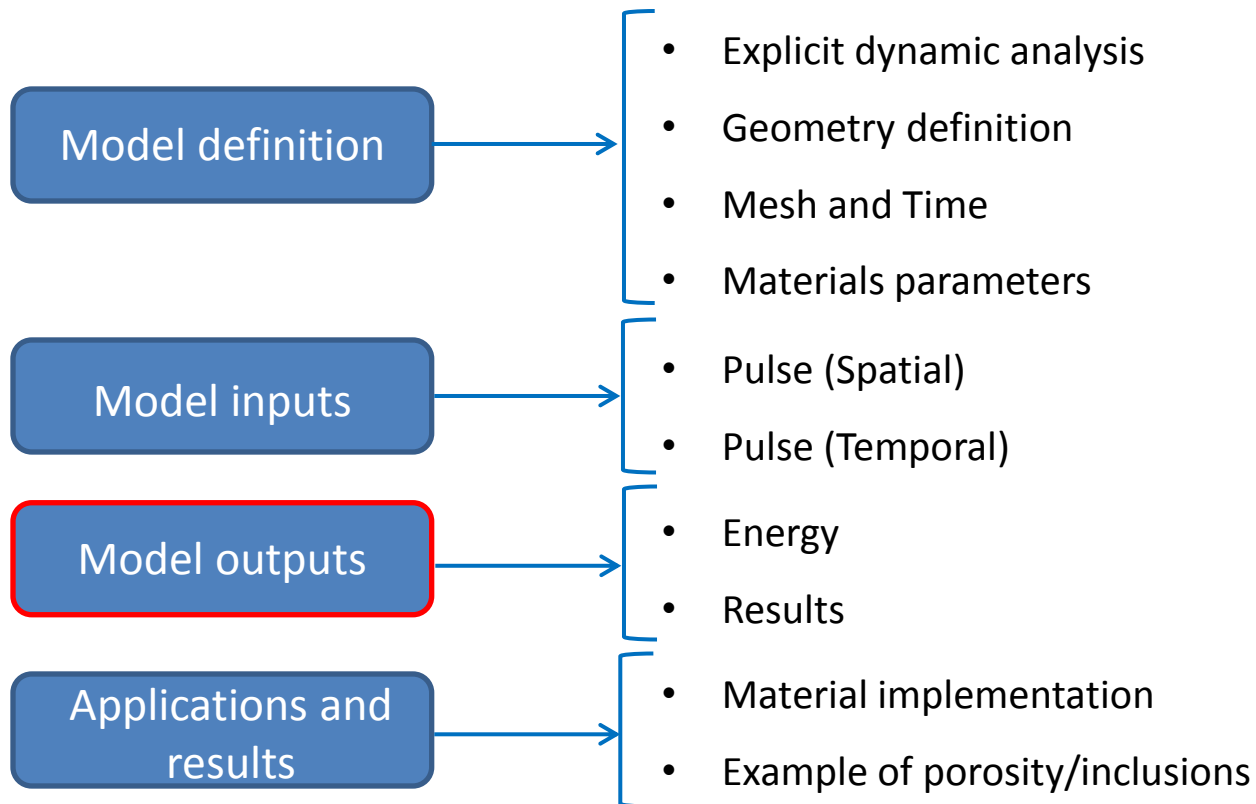
Gaussian pulse



Poor frequency content, no control
on central frequency.

Outline

Introduction

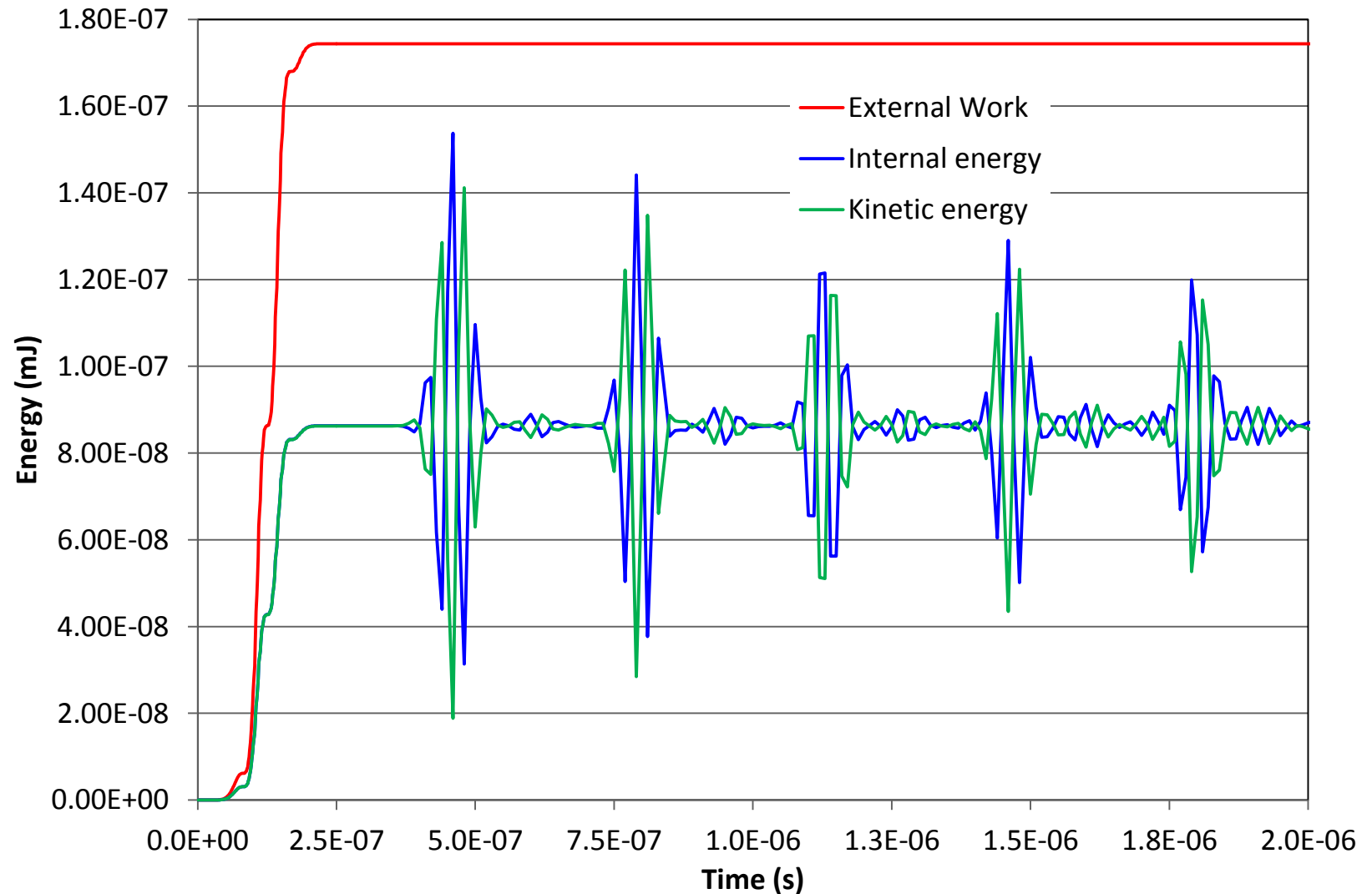


Conclusion

Model outputs

Energy

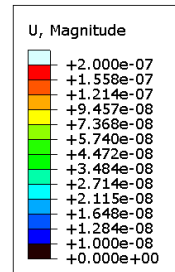
Examples with isotropic material



Model outputs

Results *Examples with isotropic material*

Contour plot

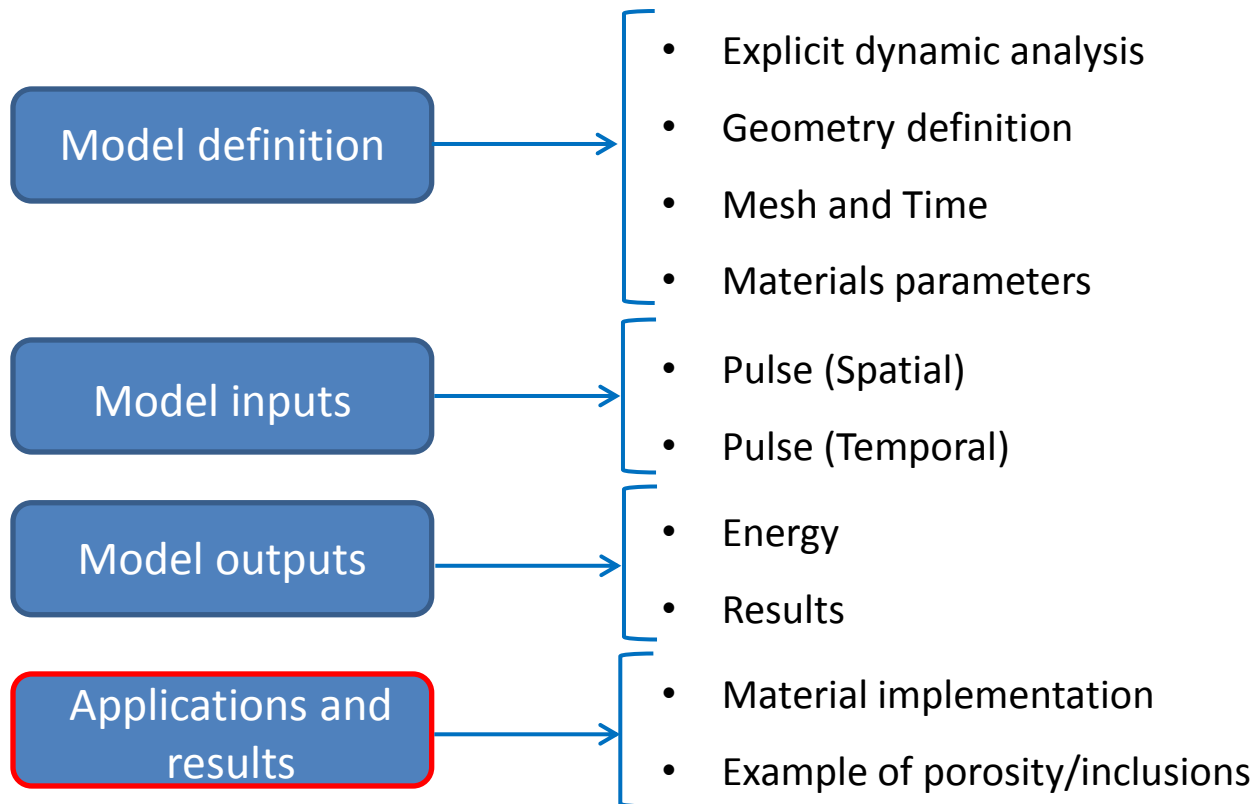


Step: PulseOn Frame: 0
Total Time: 0.000000



Outline

Introduction



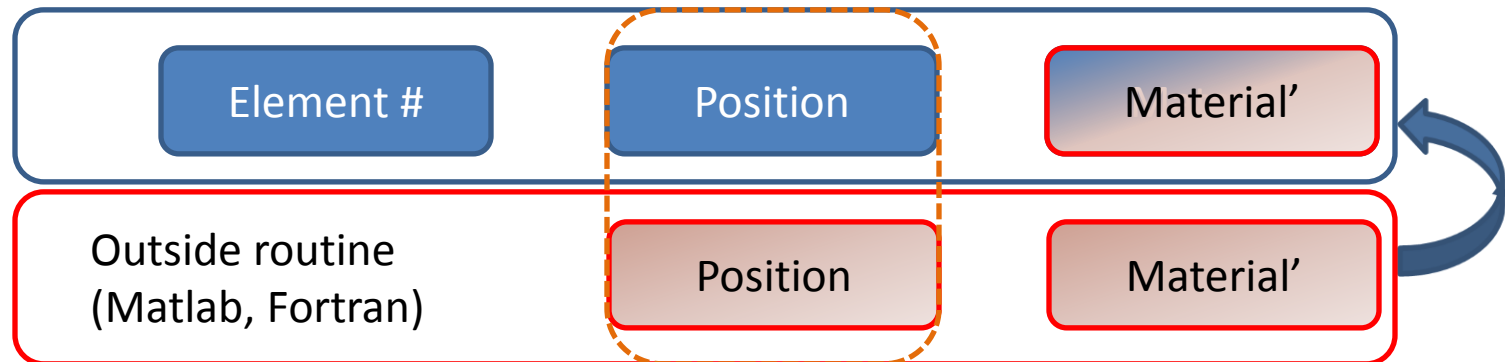
Conclusion

Applications and results

Material implementation

Creation of an input file as template

The inp text file is modified to add microstructural characteristics



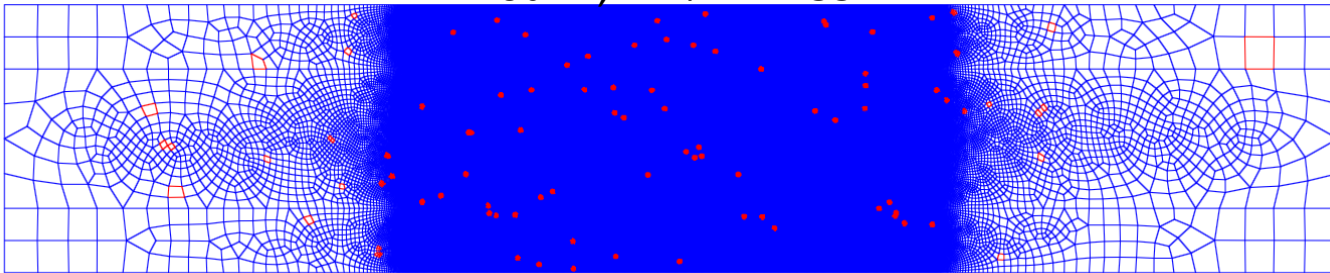
Orientation / type / position of material is defined by an outside routine, and the inp file is appropriately modified

Applications and results

Example of porosity

Ex of routine: *choose randomly a set of coordinate for spherical voids*

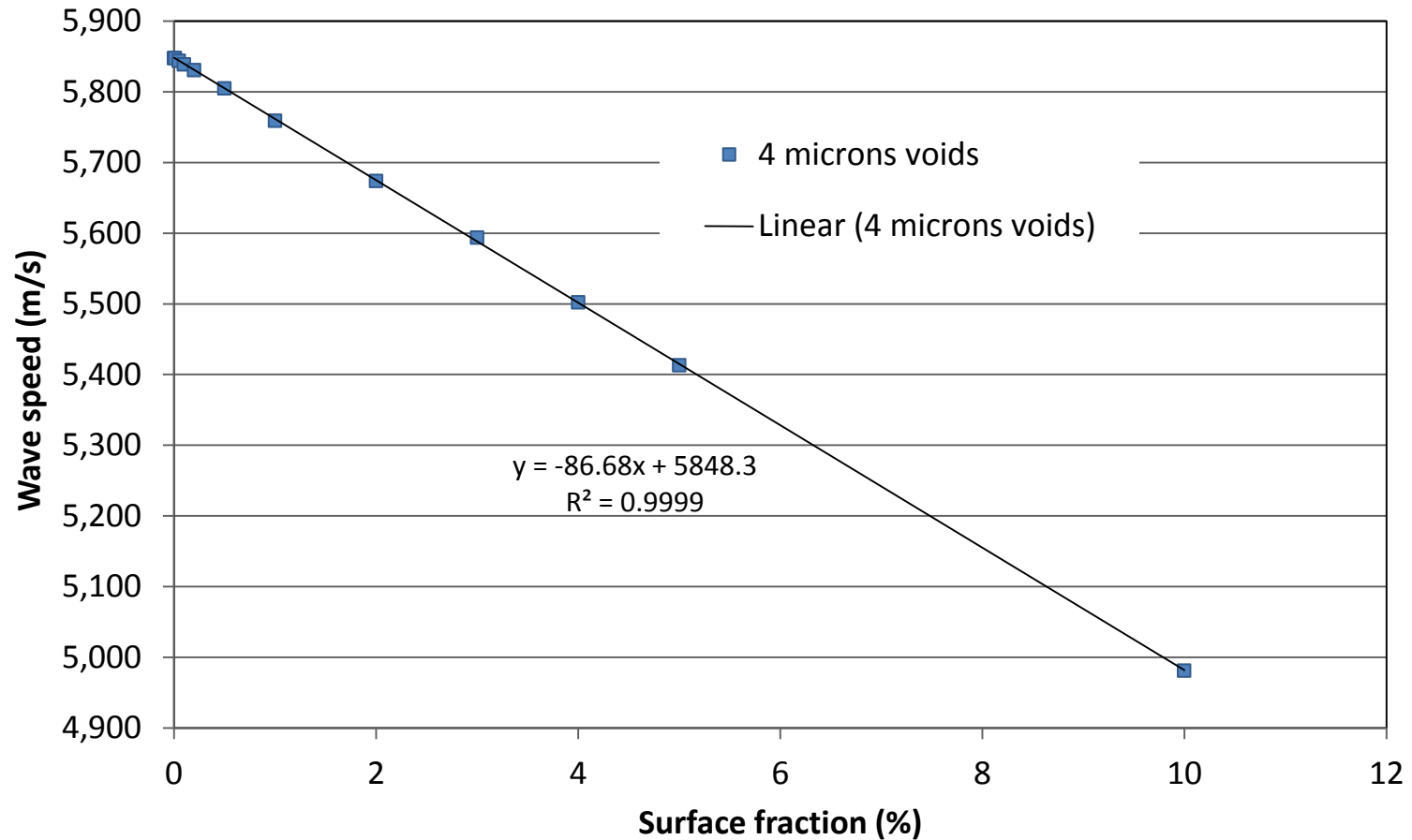
$R=20\mu\text{m}$; $f=1\%$ $N=159$



Applications and results

Example of porosity

Wave speed evolution for randomly distributed voids of element size

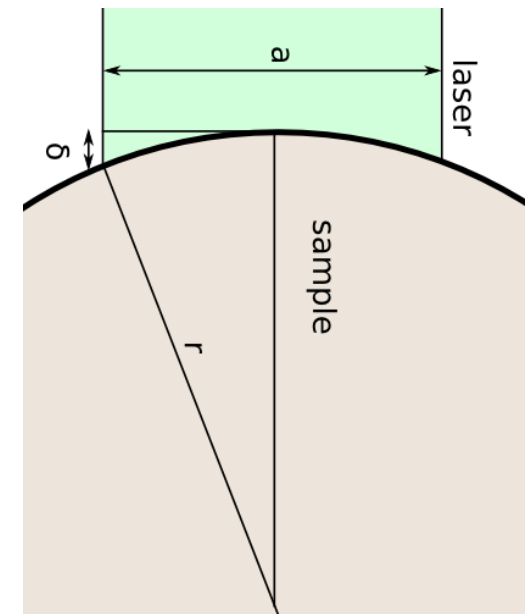
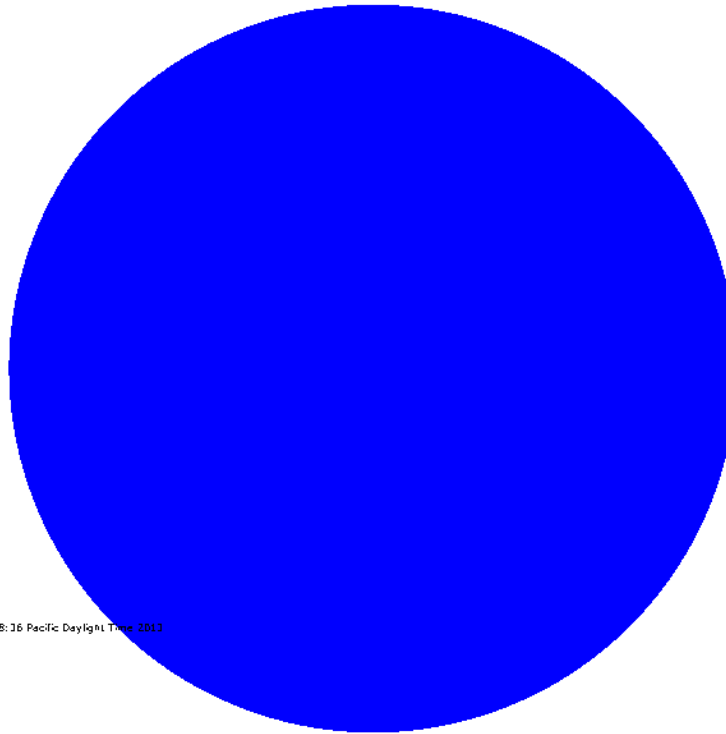
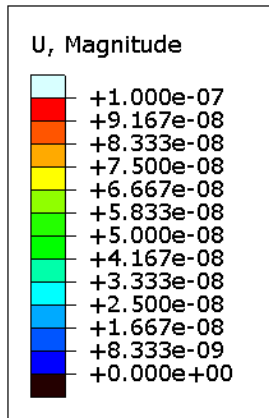


Influence of size? Distribution? Shape?

Applications and results

Effect of geometry: cylinder

Same pulse, apply on top of cylinder.



Step: PulseOn Frame: 0
Total Time: 0.000000



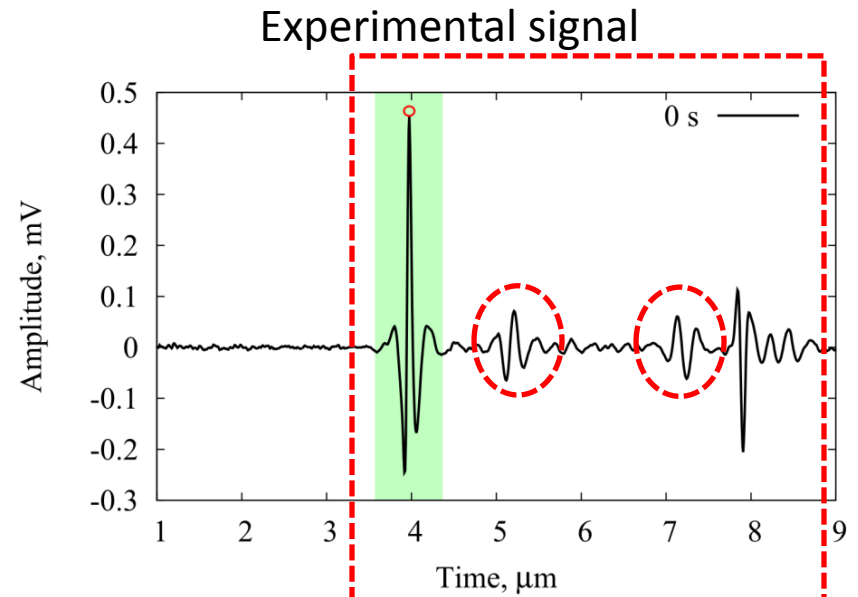
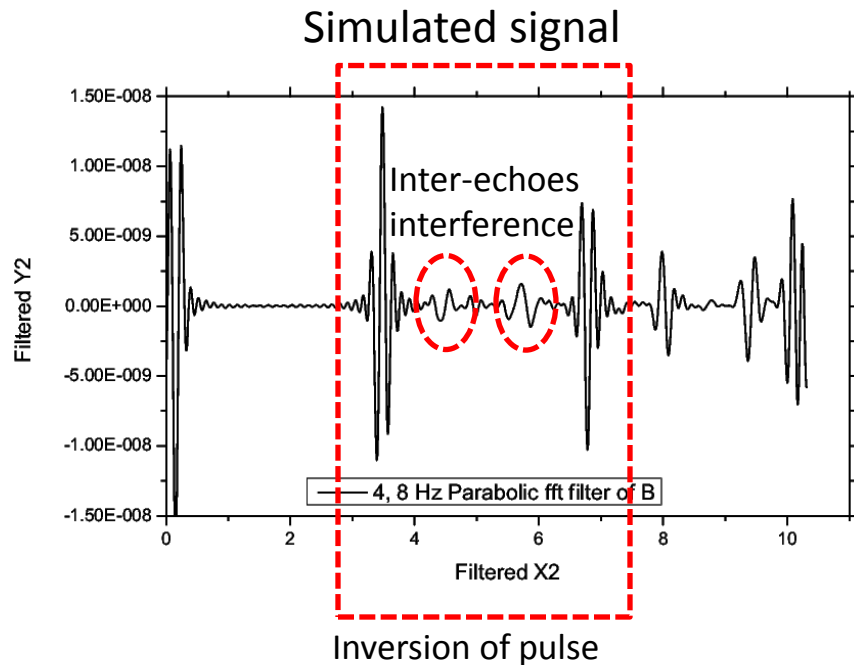
ODB: cylinder1.odb Abaqus/Explicit 6.11-2 Fri Aug 02 09:18:36 Pacific Daylight Time 2013

Step: PulseOn
Increment: 0: Step Time = 0.0
Primary Var: U, Magnitude
Deformed Var: U Deformation Scale Factor: +1.000e+00

Applications and results

Effect of geometry: cylinder

Mean displacement on top surface:



The model helps to identify geometrical artefacts



More developed application

Simulation of ultrasound propagation in anisotropic polycrystalline media

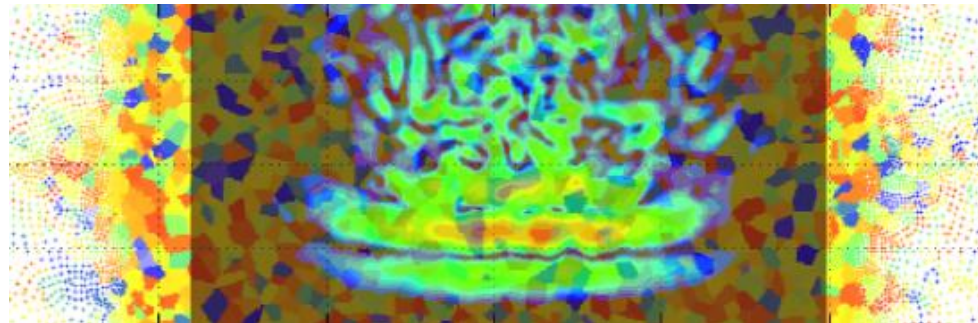
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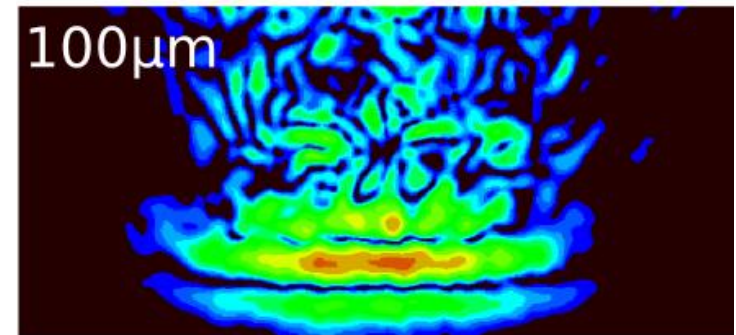
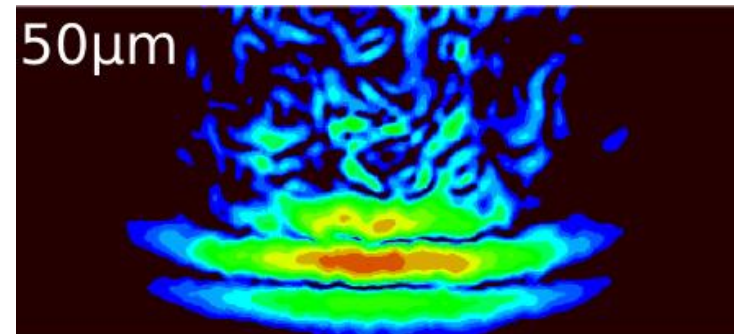
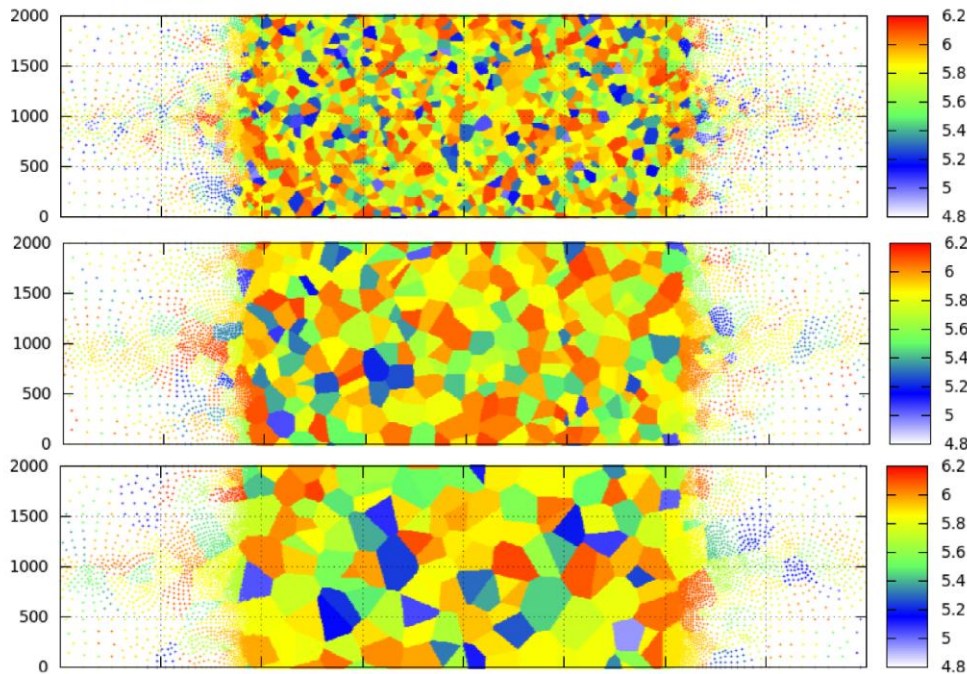
Acknowledgement

Bing Tie, Chad Sinclair, Guillaume Lefebvre, David Embury



Polycrystalline material

- ✓ Voronoi tessellation
- ✓ Generation of grain size from 20 to 300 μm with random orientation (BCC-iron)

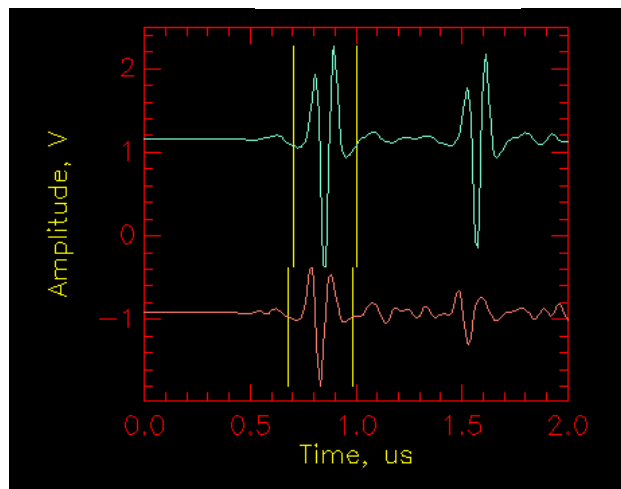




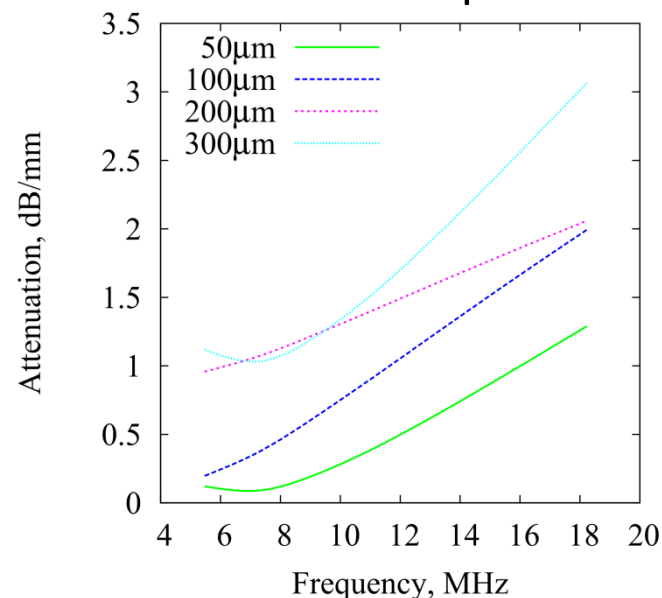
Comparing first echo, Reference 20 μm

- ✓ one echoes
- ✓ two waveforms
- ✓ Larger attenuation for larger grain size
- ✓ Examine the frequency dependence

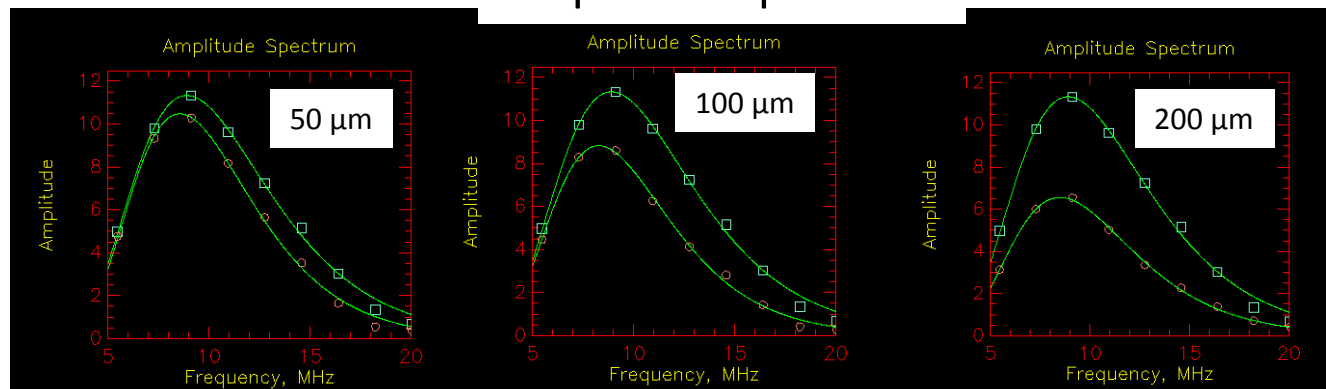
Waveform



Attenuation spectrum



Amplitude spectrum



Conclusions

✓ Three main requisites

Open resource / needs?

- ✓ **Materials properties** (stiffness, density, grain size, morphology and crystallographic orientation)

FEM tool

- ✓ **Finite Element engine** (Sample geometry, meshing, wave generation, propagation and detection of pulse)

LUMet tool

- ✓ **Waveform analysing tool** (Extract ultrasound pulse properties, velocities, attenuation spectrum)



Thank you